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## ADVERTISEMENT



# Experimental study of drop spreading on textured superhydrophilic surfaces 

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#### Abstract

The spreading dynamics of a drop deposited on a superhydrophilic micropillar array are qualitatively different from those on a smooth surface in that a thin fringe layer rapidly wicks into microstructures while the bulk collapses in the center. Here we experimentally measure the temporal evolution of the shapes of water and silicone oil drops on the superhydrophilic surfaces, and find various power laws that describe the spreading dynamics. The bulk radius increases initially but shrinks in the late stages for drainage of its volume by wicking. The fringe film tends to grow diffusively for the entire timespan of spreading with the effective diffusivity being a function of surface tension, pillar height, viscosity, and surface roughness. The entire footprint is shown to grow like $t^{1 / 4}, t$ being time, for the entire time range, which allows us to estimate the time for complete drop spreading. © 2013 AIP Publishing LLC. [http://dx.doi.org/10.1063/1.4821985]


## I. INTRODUCTION

When a solid surface is microtextured, its intrinsic wettability is magnified so that a hydrophilic surface becomes superhydrophilic and a hydrophobic surface superhydrophobic. While dynamic behavior of liquid drops on superhydrophobic surfaces has been studied extensively, ${ }^{1-4}$ the dynamics of drops deposited on superhydrophilic surfaces have drawn limited scientific interest to date. ${ }^{5,6} \mathrm{~A}$ small viscous drop on highly wettable smooth solid surfaces (e.g., a silicon oxide surface treated by oxygen plasma) maintains a spherical-cap shape at each instant during spreading ${ }^{7}$ as shown in Fig. 1(a). On the other hand, when a drop is brought into contact with a rough hydrophilic, or superhydrophilic, surface, the upper part of the drop collapses while the fringe layer wicks into the surface texture as shown in Fig. 1(b). The final shape is thus a thin film with its thickness and area defined by the geometric structures of the rough surface. McHale et al. ${ }^{8}$ observed the deviation of drop shape from a spherical cap due to drainage of bulk into a film filling the pillar gaps, but no account was given of the dynamics of each portion of the drop. The very early stage dynamics of this superwetting process were analyzed by Kim et al., ${ }^{6}$ in which the radial extent of the fringe film was small compared to the bottom radius of the bulk.

The spreading of liquid drops on highly wettable rough solid surfaces is frequently found in everyday lives, including an ink drop on paper and a rain drop impacting on fabric or soil. In HVAC (heating, ventilation, and air-conditioning) industry, the efficiency of heat and mass transfer in evaporative coolers, absorption refrigeration systems, and condensers is a sensitive function of the spreading characteristics of drops on the device surfaces. A recently suggested scheme to fabricate inexpensive microfluidic devices utilizes spreading of a biofluid on hydrophilicized paper. ${ }^{9}$ Animals living in arid environments, such as desert lizards, Moloch horridus of Australia, ${ }^{10}$ and desert horned

[^0]

FIG. 1. (a) A silicone oil drop with an initial radius 0.62 mm spreading on a smooth silicon oxide surface treated by oxygen plasma. (b) A silicone oil drop with an initial radius 0.71 mm spreading and wicking on a superhydrophilic array of square pillars of 16,15 , and $20 \mu \mathrm{~m}$ in height, width, and spacing, respectively.
lizards, Phrynosoma platyrhinos of North America, ${ }^{11}$ rely on the spreading and transport of water drops collected on their rough body surface for water ingestion. ${ }^{12,13}$

The spreading dynamics of a liquid drop are in general governed by the interaction of the collapsing bulk and the wicking fringe film. The bulk acts as both a reservoir to supply the fringe film with liquid and a region of high pressure due to its curvature. The fringe propagates radially outward through the gaps of micropillars by capillary action but also appears to extend inward in the late stages due to shrinkage of the bulk. These constitute a rich, yet unexplored problem involving the spreading (and shrinking) of a bulk drop and wicking of liquid film emanating from the source of a variable volume (bulk). Here we present quantitative measurement results of the temporal evolution of shape of drops on superhydrophilic surfaces, and then discuss the power-law behavior observed in each portion of the drop.

## II. EXPERIMENTAL

As a superhydrophilic surface, we use a micropillar array fabricated on a silicon wafer using the deep reactive ion etching process. The surface is coated with the Si-incorporated diamond-like carbon film and treated by oxygen plasma. The result is a superhydrophilic surface with controlled surface texture. For detailed process conditions, see Yi et al. ${ }^{14}$ We vary the height $(h)$, width $(w)$, and spacing $(d)$ of the square pillars as shown in Fig. 2(a), so that $\{h, w, d\} \in[1020] \mu \mathrm{m}$. Drop liquids used in the experiments are deionized water with density $\rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$, viscosity $\mu=1.3 \times 10^{-3}$ Pa s, and surface tension $\sigma=0.074 \mathrm{~N} / \mathrm{m}$, and silicone oil with $\rho=980 \mathrm{~kg} / \mathrm{m}^{3}, \mu=0.091 \mathrm{~Pa} \mathrm{~s}$, and $\sigma=0.021 \mathrm{~N} / \mathrm{m}$. The characteristic velocity $U_{c}=\sigma / \mu$, which typically appears in capillary phenomena in viscous regimes, ${ }^{15}$ is 57 and $0.23 \mathrm{~m} / \mathrm{s}$ for water and silicone oil, respectively. The equilibrium contact angles of water and silicone oil with the flat surfaces treated in the identical manner to the process above are measured to be $2.6^{\circ} \pm 0.2^{\circ}$ and $2.0^{\circ} \pm 0.6^{\circ}$, respectively, using sessile drops of $1 \mu \mathrm{l}$ volume. Drops of various radii, $a \in[0.30 .9] \mathrm{mm}$, are deposited on the horizontally situated micropillar arrays using a micropipette. The drops arrive at the substrates with a speed less than $2 \mathrm{~mm} / \mathrm{s}$ for all the cases. Since the impact Weber number, defined as $W e=\rho U^{2} a / \sigma$ with $U$ being the impact velocity, is at most $10^{-4}$, the effect of inertia compared to surface tension is negligible. A high-speed camera system records the liquid motion at a frame rate up to $100 \mathrm{~s}^{-1}$.



FIG. 2. (a) A scanning electron microscopy image of the square micropillar array. (b) Dimensions of the square micropillar array.


FIG. 3. (a) Schematic of a liquid drop deposited on a superhydrophilic micropillar array. The experimental measurement results of the bulk radius, $R_{b}$ (circle), the entire footprint, $R_{t}$ (triangle), and the radial extent of the fringe film, $L$ (square), versus time for drops of (b) water and (c) silicone oil. $[a, h, w, d]=[760,10,15,10] \mu \mathrm{m}$ for (b) and $[640,13,10,10] \mu \mathrm{m}$ for (c).

## III. RESULTS AND DISCUSSION

Since the drop consists of a central bulk and a fringe layer during spreading as illustrated in Fig. 3(a), its interaction with the solid surface can be described with the bottom radius, $R_{b}$, of the bulk and the radius of entire footprint, $R_{t}$. The radial extent of the fringe film, i.e., the distance between the edges of the bulk and the entire footprint, is $L=R_{t}-R_{b}$. Figures 3(b) and 3(c) show the experimentally measured representative temporal evolution of $R_{b}, L$, and $R_{t}$ of water and silicone oil drops, respectively. In the very early stages, all of them increase with time, $t$, indicating that the bulk increases in its bottom radius while the fringe film propagates ahead of it. The bulk radius subsequently plateaus and decreases as a significant amount of liquid in the bulk is drained into the film. Its decrease is accelerated toward the end of the spreading process when the bulk vanishes. The water drop tends to spread much faster than the silicone oil drop because of higher surface tension and lower viscosity of water. It is interesting to see that the log-log plots clearly reveal the power-law behavior of $R_{b}$ in early stages and $L$ and $R_{t}$ in the entire time range.

We use dimensional analysis to understand the measured behavior of the drops. The scaled dimensions of the drop, $R_{b} / a, R_{t} / a$, and $L / a$, must be a function of some dimensionless parameters. In addition to the dimensionless time, $t U_{c} / a$, there are three other dimensionless length scales in the problem: the scaled pillar height, $h / a$, the roughness, $r$, defined as the ratio of the actual surface area to the projected area, and the ratio of the basal area not covered by pillars to the entire projected area, $f$. Simple geometric considerations lead to $r=1+4 w h /(w+d)^{2}$ and $f=1-w^{2} /(w+d)^{2}$. Thus, we find that $X / a$ is a function of $t U_{c} / a, h / a, r$, and $f$, where $X$ can be any instantaneous dimension of the drop.

## A. Collapsing dynamics of bulk

In Fig. 4, we plot the dimensionless bulk radius, $R_{b} / a$, versus the dimensionless time $t U_{c} / a$ for different scaled parameters of surface microtexture, $h / a, r$, and $f$. In the early stages, all the data of $R_{b} / a$ collapse onto a single curve, implying that they depend only on $t U_{c} / a$ regardless of dimensions of surface microtextures. The corresponding physics were elucidated by Kim et al. ${ }^{6}$ which balanced the driving force for the bulk spreading due to capillarity, $F_{d, b} \sim R_{b} \sigma(1-\cos \theta) \sim R_{b} \sigma \theta^{2}$, with the viscous resistant force $F_{r, b} \sim \mu H_{b} R_{b}\left(\dot{R}_{b} / R_{b}\right)$, where $\theta$ is the advancing contact angle $\left(\sim H_{b} / R_{b}\right)$. Due to the high mobility of the underlying liquid film that wicks into the gaps of micropillars, ${ }^{16,17}$ the spreading dynamics of bulk differs considerably from what is expected on a smooth dry solid, Tanner's law. ${ }^{18}$ In the early stages when $H_{b} \sim a^{3} / R_{b}^{2}$, we get $R_{b} / a \sim\left(t U_{c} / a\right)^{1 / 4}$. In Appendix, we discuss the role of the mobility of the underlying liquid film in the spreading behavior of the bulk. We note that a power law different from Tanner's law for the spreading radius of a liquid drop on a thick, pre-deposited liquid film was reported in Ref. 17, which showed that the power $n$ approaches $1 / 4$ in $R_{b} \sim t^{n}$ as the film thickness increases, a result consistent with our measurements.

As time elapses, the foregoing analysis fails due to the following reasons. First, the loss of volume in the bulk due to drainage into the fringe film is no longer negligible, and thus $H_{b}$ does


| water | $h(\mu \mathrm{~m})$ | $w(\mu \mathrm{~m})$ | $d(\mu \mathrm{~m})$ | $a(\mathrm{~mm})$ | $h / a(\%)$ | $r$ | $f$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\square$ | 10 | 10 | 15 | 0.75 | 1.3 | 1.6 | 0.84 |
| $\mathbf{O}$ | 10 | 15 | 10 | 0.76 | 1.3 | 2.0 | 0.64 |
| $\mathbf{+}$ | 13 | 15 | 15 | 0.86 | 1.6 | 1.7 | 0.75 |
| $\times$ | 14 | 15 | 20 | 0.82 | 1.7 | 1.7 | 0.82 |
| $\boldsymbol{\Delta}$ | 16 | 10 | 10 | 0.77 | 2.1 | 2.6 | 0.75 |
| oil | $h(\mu \mathrm{~m})$ | $w(\mu \mathrm{~m})$ | $d(\mu \mathrm{~m})$ | $a(\mathrm{~mm})$ | $h / a(\%)$ | $r$ | $f$ |
| $\boldsymbol{D}$ | 13 | 10 | 10 | 0.64 | 2.0 | 2.3 | 0.75 |
| $\mathbf{0}$ | 13 | 10 | 15 | 0.82 | 1.6 | 1.8 | 0.84 |
| $\square$ | 13 | 10 | 20 | 0.90 | 1.4 | 1.6 | 0.89 |
| $\Delta$ | 13 | 15 | 10 | 0.68 | 1.9 | 2.2 | 0.64 |
| $\nabla$ | 14 | 15 | 15 | 0.29 | 4.8 | 1.9 | 0.75 |
| $\boldsymbol{\sim}$ | 16 | 15 | 10 | 0.83 | 1.9 | 2.5 | 0.64 |
| $\diamond$ | 20 | 15 | 10 | 0.78 | 2.6 | 2.9 | 0.64 |

FIG. 4. Temporal evolution of a dimensionless bulk radius. In the early stages ( $t U_{c} / a<300$ ), the arithmetic average of the slopes of the best-fitting lines of each experimental condition is 0.23 with the standard deviation of 0.093 .
not follow $\sim a^{3} / R_{b}^{2}$. Rather, $H_{b}$ is coupled to $L$ as well as $a$ and $R_{b}$ because the instantaneous bulk volume $\sim R_{b}^{2} H_{b}$ is given by the original drop volume $\frac{4}{3} \pi a^{3}$ minus the film volume $\pi\left(R_{b}+L\right)^{2}$. As will get clear below, $L$ is a sensitive function of surface microtextures. Second, the bulk radius shrinks while the uncompensated Young force, ${ }^{19} \sim R_{b} \sigma(1-\cos \theta)$, is continually at work. This is one of the rare examples where the contact line with the dynamic contact angle larger than the equilibrium value (near zero) recedes, posing an intriguing problem worth further exploration. Shrinkage of a drop base radius, a similar phenomenon to the one observed here, was reported for a drop that evaporates as it spreads on a completely wettable surface, ${ }^{20}$ where the base radius $R$ was shown to follow the power law $R \propto\left(t_{0}-t\right)^{y}$ with $t_{0}$ being the time when the drop totally disappears and $y$ the empirical power close to 0.5 . This system is different from ours in that the volume reduction is through the mass outflux over the entire liquid-gas interface while in the current work, the bulk volume is sucked into the gaps of micropillars only at the bulk-fringe boundary.

Since the decrease of $R_{b}$ in the late stages is caused by the drainage of liquid into the fringe film, it is natural to relate the time when $R_{b}$ starts to decrease, $\tau_{m}$, to a parameter $\beta$ signifying the ratio of the initial drop volume to drainage volume. In Sec. III B, we show that a function of the roughness, $\phi=(r-1) / r$, and the film thickness $h$ determine the film propagation rate. Taking $\beta=[a /(\phi h)]^{2}$, which will be derived below, we see that a dimensionless time for maximum bulk radius, $\tau_{m} U_{c} / a$, tends to collapse onto a single curve when plotted against $\beta$ (Fig. 5). $\tau_{m} U_{c} / a$ tends to linearly increase with $\beta$, whose slope ( 0.55 ) will be further discussed in Sec. III C. In physical terms, as the roughness and scaled pillar height increase (leading to the increase of wicking rate and


FIG. 5. Dependence of the dimensionless time when the bulk radius starts to decrease upon $\beta$.


FIG. 6. Temporal evolution of $L / a$ versus a scaled time, $D t / a^{2}$.
volume of fringe film, and thus smaller $\beta$ ), $R_{b}$ tends to start to decrease earlier in the scaled time, yielding smaller $\tau_{m} U_{c} / a$.

## B. Extension of fringe film

Now we turn to the spreading of a fringe film that goes through hemi-wicking, i.e., twodimensional wicking on a textured surface. ${ }^{21}$ Before we address the fringe film occurring in our drop deposition process, we first consider a liquid film that propagates from an infinite, stationary source. The propagation of such a film is known to exhibit the diffusive dynamics, allowing us to write $l \sim \sqrt{D t}$, where $l$ is the propagation distance from the source and $D$ is the effective diffusivity. For a straight front of liquid rising from a bath along the vertically situated superhydrophilic wall, the driving capillary and resisting viscous forces per unit width are scaled as $F_{d, f}^{\prime} \sim(r-1) \sigma$ and $F_{r, f}^{\prime} \sim \mu r i l / h$, respectively. ${ }^{6,22}$ Here subscripts $d, r$, and $f$ denote driving, resisting, and film, respectively. Then we get $D \sim \phi \sigma h / \mu$, where $\phi=(r-1) / r$. A similar model applies to an axisymmetric propagation of a film from a stationary point source like a pen ${ }^{22}$ with $F_{d, f} \sim(r-1) \sigma R_{s}$ and $F_{r, f} \sim \mu \dot{R}_{s} R_{s}^{2} r / h$, which yields the radius of a circular blot, $R_{s} \sim \sqrt{D t}$.

The temporal evolution of the radial extent of fringe film, $L$, during the drop spreading considered here needs to be treated with caution. The bottom radius of the liquid reservoir, or the bulk, grows and subsequently shrinks while the outer edge propagates. Thus, $L$ must be measured between the edges of bulk and entire footprint, both of which move with time: $L(t)=R_{t}(t)-R_{b}(t)$. Motivated by the fact that the dimensionless timescale obtained from the diffusive dynamics analysis, $D t / a^{2}$, is expressed as the product of the following dimensionless parameters, $\phi, h / a$, and $t U_{c} / a$, we plot $L / a$ versus $D t / a^{2}=\phi(h / a) t U_{c} / a$ in Fig. 6 to find that all the data tend to collapse onto a straight line. The arithmetic average of the slopes of the best-fitting lines for each experimental condition is 0.60 with the standard deviation of 0.078 . This is in reasonable agreement with the diffusive behavior, $L \sim t^{1 / 2}$, as previously observed by Courbin et al. ${ }^{5}$ for the similar system. The diffusive dynamics can be explained as the following: balancing $F_{d, f} \sim R_{t}(r-1) \sigma$ with $F_{r, f} \sim \mu r U\left(R_{t}^{2}-R_{b}^{2}\right) / h$ while taking $U \sim \dot{L}$ gives $L \dot{L} \sim(\phi \sigma h / \mu)\left(1+R_{b} / R_{t}\right)^{-1}$. Because $\left(R_{b} / R_{t}\right) \ll 1$ when $L / a>1$, we get $L \sim(D t)^{1 / 2}$. The empirical relation between $L / a$ and $D t / a^{2}$ can be established as the following via the least squares method:

$$
\begin{equation*}
\frac{L}{a}=0.36 \sqrt{\frac{D t}{a^{2}}} . \tag{1}
\end{equation*}
$$

## C. Spreading of entire footprint

The radius of entire footprint, $R_{t}$, is a sum of the bulk radius and fringe extension: $R_{t}=R_{b}+L$. In the early stages when $R_{b} \gg L, R_{t}$ must follow the behavior of $R_{b}$, and thus it is natural to write


FIG. 7. The scaled radius of the entire footprint, $R_{t} / a$, versus a scaled time, $t U_{c} / a$. The arithmetic average of the slopes of the best-fitting lines of each experimental condition is 0.28 with the standard deviation of 0.018 .
$R_{t} / a \sim\left(t U_{c} / a\right)^{1 / 4} .{ }^{6}$ Surprisingly, when plotting $R_{t} / a$ versus the scaled time $t U_{c} / a$ as in Fig. 7, we find that all the experimental data tend to collapse onto a single straight line with a slope of $1 / 4$ even beyond the early stages. Thus, the radius of entire footprint, which spreads like $t^{1 / 4}$ throughout the time, can be expressed by the following general empirical relationship using the dimensionless parameters:

$$
\begin{equation*}
\frac{R_{t}}{a}=0.62\left(\frac{t U_{c}}{a}\right)^{1 / 4} \tag{2}
\end{equation*}
$$

There are two remarkable features in this relationship. First, the spreading of entire footprint is independent of the detailed surface structures, but only depends on the liquid properties ( $\sigma$ and $\mu)$ and the initial drop radius. That is, $R_{t} / a$ depends only on $t U_{c} / a$, not on the other independent dimensionless parameters such as $h / a, r$, and $f$. Second, while the fringe film that propagates like $t^{1 / 2}$ as a function of $\phi$ dominates over $R_{b}$ in the late stages, such an effect is not pronounced in the spreading rate of $R_{t}$. As mentioned above, the temporal evolutions of $R_{b}$ and $L$ are interrelated because the mass of the initial drop should be conserved. The increase in the fringe area causes the deceleration of the bulk spreading and eventually the shrinkage of the bulk. The different power laws of $L$ and $R_{t}$ are rationally explained by supposing that the temporal evolution of $R_{b}$ absorbs the effects of $L$.

Using the empirical relation (2), we can further understand the behavior of $R_{b}$ that undergoes growth and subsequent decrease during the course of drop spreading. Since $R_{b}=R_{t}-L$, we


FIG. 8. The scaled bulk radius, $R_{b} / a$, plotted according to Eq. (3). The lines plot Eq. (3) for each condition.


FIG. 9. The dimensionless time for complete spreading versus $[a /(f h)]^{2}$. The line plots Eq. (5).
empirically get

$$
\begin{equation*}
\frac{R_{b}}{a}=A\left(\frac{t U_{c}}{a}\right)^{1 / 4}-B \frac{\sqrt{D t}}{a} \tag{3}
\end{equation*}
$$

where $A=0.62$ and $B=0.36$. It follows that when $t \ll(A / B)^{4} a^{3} \mu /\left(\phi^{2} \sigma h^{2}\right)$, the first term in the left-hand side of Eq. (3) dominates, and thus we recover $R_{b} / a \sim\left(t U_{c} / a\right)^{1 / 4}$. We compare Eq. (3) with the experimental data in Fig. 8, to find reasonable agreement between them. By differentiating Eq. (3) with $t$, we find the time, $\tau_{m}$, at which $R_{b}$ reaches the maximum:

$$
\begin{equation*}
\frac{\tau_{m} U_{c}}{a}=\left(\frac{A}{2 B}\right)^{4} \frac{1}{\phi^{2}}\left(\frac{a}{h}\right)^{2} \tag{4}
\end{equation*}
$$

As mentioned earlier, $R_{b}$ starts to decrease earlier with the increase of $\phi$ and $h / a$ because of promoted drainage of liquid into fringe, whose tendency has been experimentally observed in Fig. 5. We note that the coefficient of proportionality, $[A /(2 B)]^{4}=0.55$ in Eq. (4), agrees well with the slope found in Fig. 5.

The simple dependency of $R_{t} / a$ on the dimensionless time $t U_{c} / a$ also allows us to predict the time taken for a drop to complete its spreading. Balancing the original drop volume, $\frac{4}{3} \pi a^{3}$, with the volume of liquid film that fills the gaps of the pillars, $\pi R_{t}^{2}(t) h f$, gives the time for complete spreading, $\tau_{e}$ :

$$
\begin{equation*}
\frac{\tau_{e} U_{c}}{a}=\frac{16}{9 A^{4}} \frac{1}{f^{2}}\left(\frac{a}{h}\right)^{2} \tag{5}
\end{equation*}
$$

where the proportionality constant $16 /\left(9 A^{4}\right)=12$. We see reasonable agreement between Eq. (5) and the experimental measurements in Fig. 9. The spreading takes shorter on the substrates with sparse (high $f$ ) but tall pillars (high $h / a$ ), while it takes longer on the substrates with short pillars of a high areal density.

## IV. CONCLUSIONS

We have presented the experimental measurement results of the temporal evolution of drop shapes on superhydrophilic micropillar arrays, and found various power laws between dimensionless parameters describing the spreading dynamics. Beyond the early stages of spreading that were covered previously, ${ }^{6}$ we have measured and analyzed the dynamics of the bulk, fringe film, and entire footprint for the whole timespan of spreading. The bulk radius increases initially but decreases in the late stages for drainage of its volume into the microstructure-such decrease is hastened as the roughness and pillar height increase. The fringe film tends to grow diffusively with the effective
diffusivity being a function of surface tension, viscosity, pillar height, and roughness. The entire footprint is shown to simply grow like $t^{1 / 4}$ for the entire time range, which allows us to find empirical relationships for the temporal evolution of the bulk radius and the time for entire spreading.

The experimental data and power laws revealed in this work can be useful in numerical simulations which have begun to be conducted recently for the spreading of liquids on micropillar arrays. ${ }^{23-25}$ Those computational works are in turn anticipated to help us to understand how the bulk height $H_{b}$ evolves with time in addition to the bottom radii treated here. As experimentally found by McHale et al., ${ }^{8}$ the superwetting behavior, i.e., the fast spreading of the fringe film ahead of the collapsing bulk, can also be observed for rough surfaces which are partially wettable when flat. This was qualitatively observed in the experiments performed through this work, although a detailed analysis how the decreased hydrophilicity affects the spreading rates of each portion of drop calls for further study. Our results can be practically used to understand the spreading of liquid drops on HVAC equipments which are frequently covered with microroughness to enhance surface wettability, and to predict the biosample transport in paper-based microfluidic devices.

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## APPENDIX: BULK SPREADING ON A PRE-WETTED PILLAR ARRAY

To test the effects of an underlying liquid layer on the dynamic behavior of a drop, we measured the spreading of a drop on a textured superhydrophilic solid preimpregnated by the same liquid. We used a micropillar array with $h=13, w=10$, and $d=15 \mu \mathrm{~m}$ formed on a square silicon wafer measuring $20 \mathrm{~mm} \times 20 \mathrm{~mm}$. We pre-wetted the surface by depositing a silicone oil drop, which wicked into the gaps of the pillar array. By changing the size of the silicone oil drops, we changed the area of pre-wetted surface, so that one surface (surface I) was entirely wetted by silicone oil with the wet area being $400 \mathrm{~mm}^{2}$ and the other surface (surface II) was partially wetted with the wet area being $70 \mathrm{~mm}^{2}$. When a silicone oil drop with the radius $a=0.82 \mathrm{~mm}$ was deposited on the fully pre-wetted surface (I), no further wicking was possible because all the gaps between the pillars had already been filled with the liquid. We found that the drop deposited on surface I spreads with the bottom radius $R_{b}$ following Tanner's law ( $R_{b} \sim t^{1 / 10}$ ) as shown in Fig. 10. However, when a drop was deposited on the partially pre-wetted surface (II), $R_{b}$ increased like $t^{1 / 4}$ in the early stages just


FIG. 10. Temporal evolution of the dimensionless bulk radius on dry and pre-wetted micropillar arrays with $h=13, w=10$, and $d=15 \mu \mathrm{~m}$. Triangles, circles, and squares correspond to the values of $R_{b} / a$ on surfaces I and II and the dry micropillar array, respectively.


FIG. 11. Schematic illustrations of the flows associated with the bulk spreading on micropillar arrays. (a) A drop spreading on a fully pre-impregnated pillar array (surface I). (b) A drop spreading on a partially pre-impregnated pillar array (surface II). (c) A drop spreading on a dry pillar array.
as $R_{b}$ of a drop deposited on the dry micropillar array, Fig. 10. These experiments reveal the crucial role of mobility of the underlying liquid layer in the spreading behavior of the drop or bulk.

As schematically illustrated in Fig. 11(a), the drop deposited on surface I spreads on a pillar array whose gaps are filled with nearly immobile liquid film, thus the velocity gradient is dominantly established across the drop height giving the viscous force as $\sim \mu R_{b}^{2} \dot{R}_{b} / H_{b}$. Balancing this force with the driving force $\sim R_{b} \sigma(1-\cos \theta) \sim R_{b} \sigma \theta^{2}$ leads to Tanner's law: $R_{b} / a \sim\left(U_{c} t / a\right)^{1 / 10}$. The nanoscopic precursor film that emerges ahead of the bulk of the drop does not alter this scaling law. ${ }^{17}$ On the other hand, the drop deposited on either surface II or the dry pillar array exhibits a power law of $R_{b}$ clearly different from that on surface I because of the flow within the underlying liquid layer. As can be hinted by the facts that the drop collapses into the underlying prewetted area (surface II) and that the fringe layer always precedes the bulk radius on dry pillar arrays (Fig. 11(c)), the bulk on surface II and the dry surface rides a highly mobile liquid layer that wicks into the gaps of superhydrophilic micropillar arrays. The micropillar array exerts viscous shear stresses on the liquid, but they are taken into account by the wicking of the liquid film that infiltrates the pillar gaps. Thus, the dominant velocity gradient within the bulk is given by $\dot{R}_{b} / R_{b}$, which results in the power law of $R_{b} \sim t^{1 / 4}$, consistent with experiment.
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